

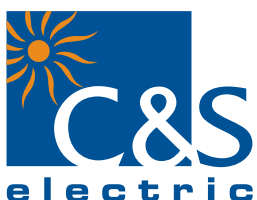
We touch your **electricity** everyday!

CSEnEX-I

INTELLIGENT MEASURING AND PROTECTION DEVICE



Catalog



PMD Division

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1) Introduction

CSENEX Series offers a compact Multi-functional Over-current protection solution for Feeder, Generator, Motor & Transformer segment.

CSENEX-I Family of protective relays are numeric relays that provides multi protection and monitoring with reliable and fast protection solution in a single unit.

In this family of CSENEX series, the CSENEX-I is an advanced feeder protection solution which has fast, sensitive and secure protection for feeder internal & external faults.

CSENEX-I offers different model based features to cover the wide range of user.

2) Features

- 1A & 5A rated CT input (programmable)
- Draw out with self CT shorting
- Programmable auto-reclosing by selecting number of cycles for a particular fault
- Relay is equipped with self-supervision function
- Event recorder
- Fault recorder
- DI/DO programmable matrix
- Protection blocking through DI
- Communication (Local & Remote)

3) Application

The CSENEX-I relays have been designed for controlling, protecting and monitoring industrial, utility distribution networks and substations. They can also be used as part of a protection scheme for feeders, transformers and generators.

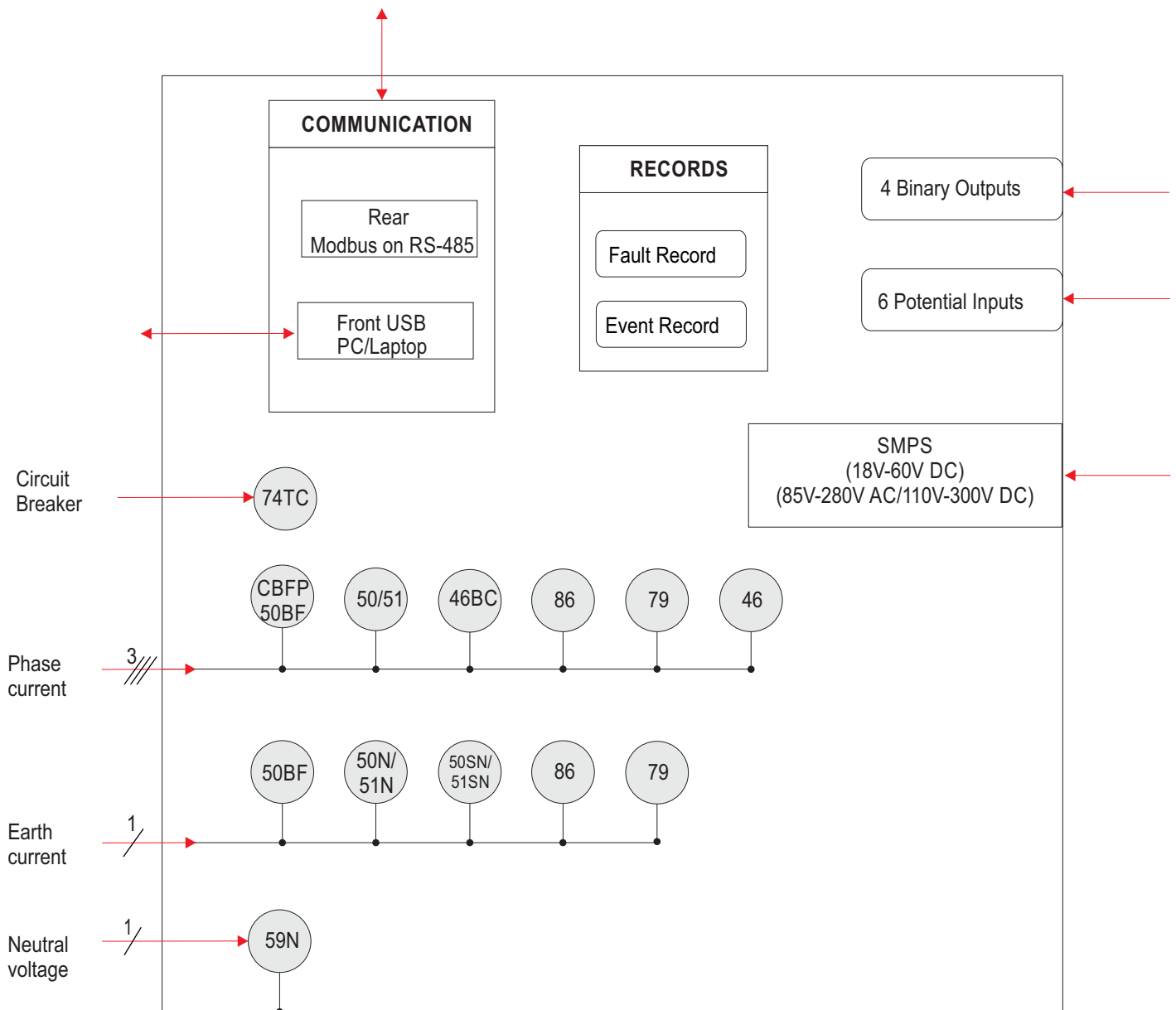
4) Hardware

- Digital Signal Processor based numeric design
- Measures true RMS with DFT filter
- 1 A & 5A common current terminal and programmable
- 4 Current analog inputs for phase & earth fault current
- 6 Digital Inputs
- 4 Digital Outputs
- 16 x 4 Alpha-numeric LCD
- 8 LEDs at pickup and trip on fault + 3 LEDs with special function of 3 control keys
- RS-485 & USB communication

5) Protection Features

- Three phase time over current protection
- Three phase instantaneous protection
- Earth time over-current
- Earth instantaneous over-current
- Current unbalance / Negative Phase Sequence
- Broken conductor
- Residual over-voltage (neutral displacement)
- Circuit breaker failure protection
- Trip Circuit supervision
- Auto-Recloser

6) Functional Diagram



(Figure 1)

Protection Function

Three Phase Over-current Protection

The independent two stages are available for phase fault protection. For I> the user may independently select definite time delay or inverse time delay with different type of curves. The second Hi-Set stage can be configured with definite time only.

Earth Fault Protection

The independent two stages are available for earth fault protection. For first stage (Ie>) the user can select definite time delay or inverse time delay with different type of curves. The second Hi-Set stage can be configured with definite time only.

If neutral displacement option is selected then earth fault pick-up is considered only when neutral voltage is above the set level.

Broken Conductor Protection*

For giving this protection the ratio of -ve phase sequence current and +ve phase sequence current is measured. The delay timer starts when the ratio exceeds the set value and tripping is initiated as soon as set time is elapsed.

Current Unbalance (46)

It contains the inverse and definite time characteristics. This protection works exactly in the same way as phase over current but I2> is combination of all three current. Its amplitude also depends on the phase angle.

$$3|I_2| = |I_a + a^2 I_b + a I_c|$$

Where a = $1 \angle 120^\circ$

Relay Latching (86)

Relay can be configured to Latch /Unlatch depending on configuration.

(Latching is possible in presence of Auxiliary supply voltage only)

Trip Circuit Supervision

This feature continuously supervises trip circuit of both pre closing and post closing conditions in circuit breaker. It detects tripping mechanism failure like circuit breakage contact degeneration in wires, contacts and coils.

Note: Trip counter is incremented on the basis of getting trip command from relay and not on the basis of external mechanism (circuit breaker) operation.

Harmonic Blocking

Harmonic setting is by default 25% of injected current and takes 4 cycle to sense the harmonic injection. Phase/Earth Harmonics can be Blocked/Unblocked & time setting can also be edited through HMI. If the Pickup current has %harmonics above 25%, the protection will blocked for the harmonics blocking time. Tripping occurs according to the higher time setting i.e. if the harmonics time setting is greater it will trip according to the harmonics time setting otherwise according to the fault time setting.

Circuit Breaker Failure Protection

The CB Failure Protection is based on supervision of phase and earth currents after tripping events. The test criterion is whether all phase currents have dropped to less than 5% of In within tCBFP. If one or more of the phase currents have not dropped to specified current within this time, CB failure is detected and the assigned output relay is activated.

Auto Recloser Strategy*

As 80% of faults in overhead lines are transient, the use of the auto recloser is very advantageous. Automatic auto-recloser allows a substation to operate unattended. The number of visits on site to manually reclose a circuit breaker after a fault, can then be substantially reduced. This feature gives an important advantage for substations supervised remotely.

Typically this auto reclose (AR) sequence of Instantaneous Trip(s) and Reclose Delays (Dead times) followed by Delayed Trip(s) provide the automatic optimum method of clearing all types of faults i.e. both Transient and Permanent, as quickly as possible and helps in improving the up time of the network in service.

DI Inputs:

AR Blocking - To block the auto recloser through remote DI
CB Close DI - To get the circuit breaker status
CB Ready - To get the CB ready or to give the closing command

Configurable Outputs:

79 AR Close CB
79 Lockout

AR-Blocked:

Unit changes immediately to "AR-blocked" status when an external AR Blocking DI is applied or internal EXIT is chosen for AR cycle in HMI. No Auto reclosing is possible in "AR-blocked" status.

Activating of AR:

Prior to every AR it is possible to select which kind of tripping (I> or I>>, Ie> etc.) will lead to automatic re-closing. This can be separately fixed for each protection.

Dead time (td): Starts with the off signal of the circuit breaker. No closing command to the circuit breaker is given till expiry of the set dead time.

User programmable dead times are available for each protection trip operation.

The dead time is initiated when the trip output contact resets, the pickup is reset and the CB is open.

The CB close output relay is energized after the dead time has elapsed if CB ready input is present.

The dead time (dead time td1, dead time td2 dead time td3 dead time td4) starts when the feedback on 'CB CLOSE DI' is not available.

NOTE: Trip Test is available in HMI to check all LEDs and Digital Output (Relay)

Reclaim time (tr):

This is the time during which after switching on or after AR a subsequent reclosing is prevented.

If the number of the set shots is reached, the relay is locked for this time after the last re-closing attempt.

If CB Ready DI is not available relay will not generate closing command.

If the circuit breaker does not trip again, the auto re-close cycle resets to original STATE-1 at the end of the reclaim time.

If the protection operates during the reclaim time of the relay:

* either advances to the next AR cycle that is expected in next auto re-close state or

* if all the programmed re-closer attempts have been accomplished, it locks out.

The reclaim time is started with the automatic closing command.

Once a CB has re-closed and remained closed for a specified time period (the reclaim time), the AR sequence is reinitialized and a successful close output issued. A single common reclaim time is used (Reclaim Timer). when an auto re-close sequence does not result in a successful re-closure the relays goes to the lock out state.

Starting Condition for Auto Re-closer

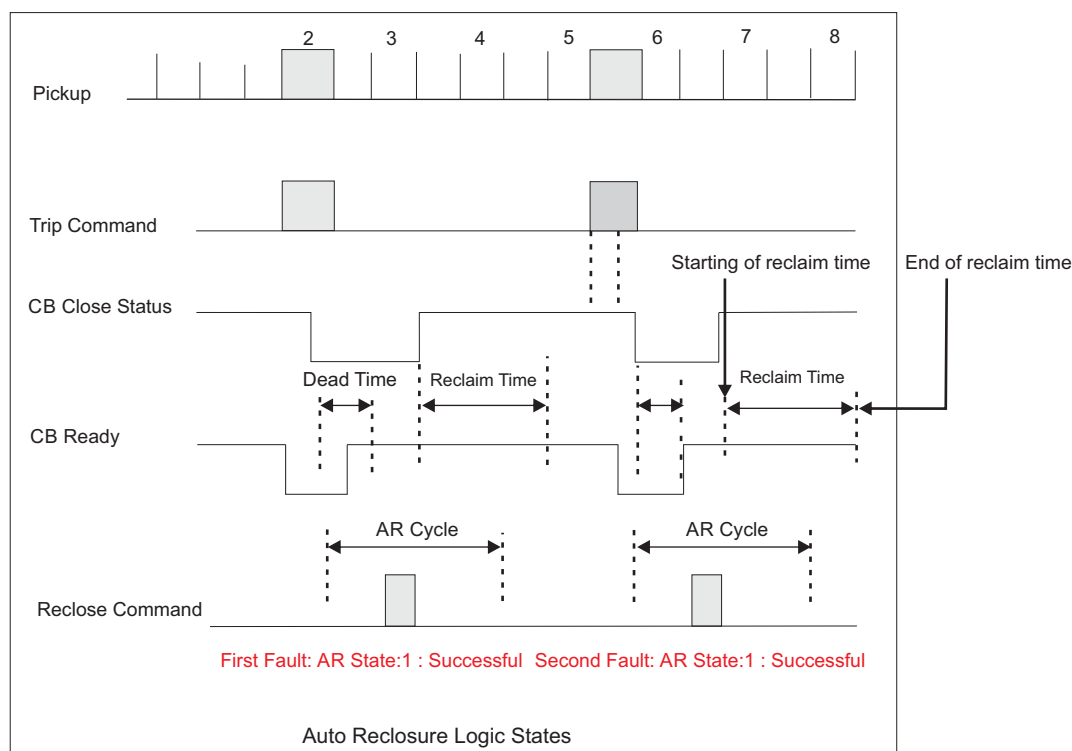
- 1) AR should be enabled by manual setting.
- 2) AR blocked DI is not available
- 3) Respective protection AR cycle should not in exit condition.

Lock out State

Lockout state of the breaker means no further attempts to AR in these conditions

- 1) Lockout occurs when all auto re-closure attempts are over and protection operates during the final Reclaim Time.
- 2) If CBFP failure appeared in relay (if CBFP enable).
- 3) At the end of the each reclaim timer if the CB is in the open position (Close DI is not present).
- 4) If a Close pulse of AR relay is given and the CB fails to close through close DI input or expiry of Trip Contact Sense time.
- 5) If a open pulse given to CB and CB fails to open in between Trip Contact Sense time.

In any of these cases, Manual reset will be required to reinitiate the AR.



(Figure 2)

Self Supervision Function :

One Relay can be assigned as Alarm Relay for Self Supervision. If any failure happens in the relay internal supply these contact will change its status. This contact can be configured to trip the upstream breaker.

7) Fault Record

CSENEX-I records last 10 faults in its non volatile memory with it's time stamp. Each record has the following information:

fault Format

[F] IL1 : 00.00A
[F] IL2 : 00.00A
[F] IL3 : 00.00A
[F] Ie : 00.00A
HOUR MIN : HH:MM
SEC mSEC : Sec:mSec
F-TYPE : FAULT TYPE

Where

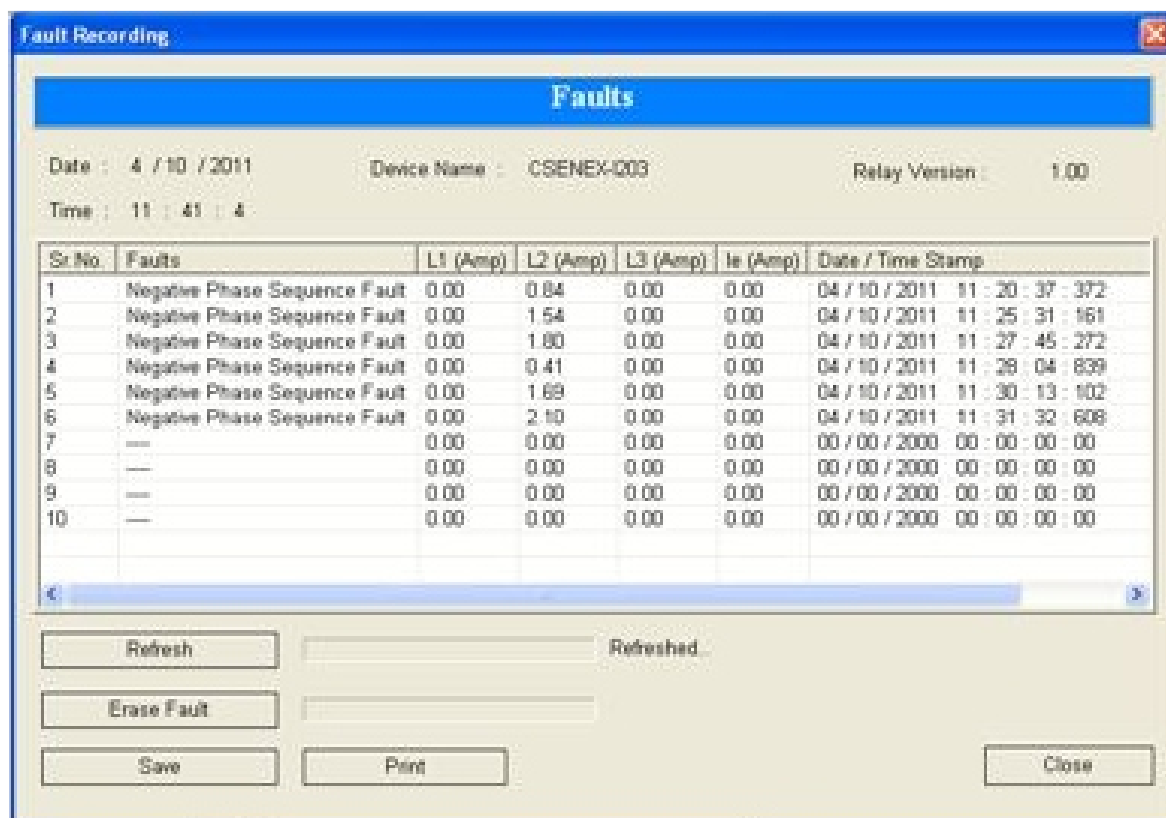
[F][ILx] Magnitude of phase current's.

[F]Ie Magnitude earth fault current's

F-Type Origin of fault (over current, negative phase sequence, etc.) (See Figure 3)

whenever the available memory space is exhausted the new fault automatically over writes the oldest fault. When the relay trips the description of fault in the feeder will appears on the LCD screen automatically and by pressing \downarrow key one can easily get all the detailed information of that fault.

The user can view the fault record either via the front USB interface software or remotely via the RS-485 communication.(See figure-3)



The screenshot shows a software window titled "Fault Recording" with a sub-header "Faults". It displays the following information:

- Date : 4 / 10 / 2011
- Device Name : CSENEX-003
- Relay Version : 1.00
- Time : 11 : 41 : 4

Below this information is a table with 7 columns: Sr.No, Faults, L1 (Amp), L2 (Amp), L3 (Amp), Ie (Amp), and Date / Time Stamp. The table contains 10 rows of data, with the first 5 rows showing "Negative Phase Sequence Fault" and the remaining 5 rows showing "—".

| Sr.No | Faults | L1 (Amp) | L2 (Amp) | L3 (Amp) | Ie (Amp) | Date / Time Stamp |
|-------|-------------------------------|----------|----------|----------|----------|-----------------------------------|
| 1 | Negative Phase Sequence Fault | 0.00 | 0.84 | 0.00 | 0.00 | 04 / 10 / 2011 11 : 20 : 37 : 372 |
| 2 | Negative Phase Sequence Fault | 0.00 | 1.54 | 0.00 | 0.00 | 04 / 10 / 2011 11 : 25 : 31 : 161 |
| 3 | Negative Phase Sequence Fault | 0.00 | 1.80 | 0.00 | 0.00 | 04 / 10 / 2011 11 : 27 : 45 : 272 |
| 4 | Negative Phase Sequence Fault | 0.00 | 0.41 | 0.00 | 0.00 | 04 / 10 / 2011 11 : 28 : 04 : 839 |
| 5 | Negative Phase Sequence Fault | 0.00 | 1.69 | 0.00 | 0.00 | 04 / 10 / 2011 11 : 30 : 13 : 102 |
| 6 | Negative Phase Sequence Fault | 0.00 | 2.10 | 0.00 | 0.00 | 04 / 10 / 2011 11 : 31 : 32 : 608 |
| 7 | — | 0.00 | 0.00 | 0.00 | 0.00 | 00 / 00 / 2000 00 : 00 : 00 : 00 |
| 8 | — | 0.00 | 0.00 | 0.00 | 0.00 | 00 / 00 / 2000 00 : 00 : 00 : 00 |
| 9 | — | 0.00 | 0.00 | 0.00 | 0.00 | 00 / 00 / 2000 00 : 00 : 00 : 00 |
| 10 | — | 0.00 | 0.00 | 0.00 | 0.00 | 00 / 00 / 2000 00 : 00 : 00 : 00 |

At the bottom of the window, there are buttons for "Refresh", "Erase Fault", "Save", "Print", and "Close". A "Refreshed" status bar is also present.

(Figure 3) (Fault Data Recording on PC software)

8) Event Record

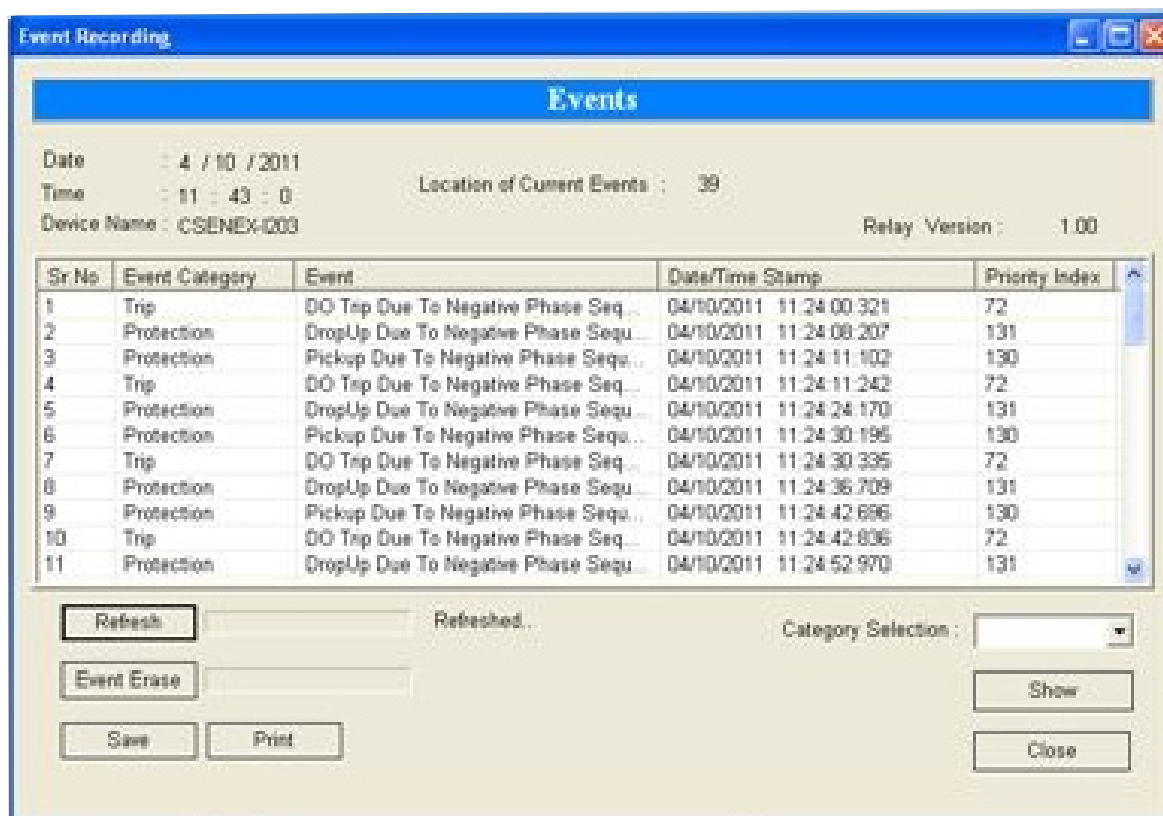
The unit stores in non volatile memory the last 50 events. When the available memory space is exhausted, the new event automatically overwrites the oldest event which can be retrieved from a PC, with the following format:

EVENT : EVENT NUMBER
 HOUR : HH:MM
 SEC mSEC : SEC:mSEC
 DATE : DD/MM/YY
 E-TYPE : TYPE OF EVENT

- * Date and time of the event
- * Descriptive text of the even

The user can view event records via the front USB interface software (See Figure 4)

- * Description of event number available in event list or in front end software



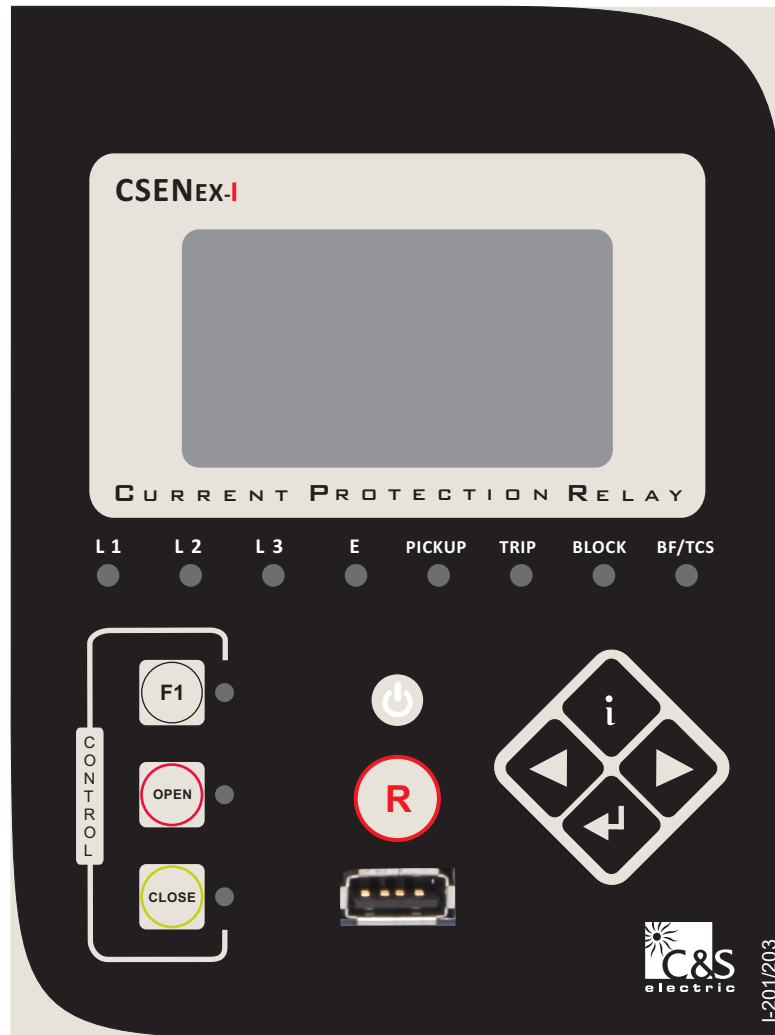
| Sr No | Event Category | Event | Date/Time Stamp | Priority Index |
|-------|----------------|--------------------------------------|-------------------------|----------------|
| 1 | Trip | DO Trip Due To Negative Phase Seq... | 04/10/2011 11:24:00.321 | 72 |
| 2 | Protection | DropUp Due To Negative Phase Sequ... | 04/10/2011 11:24:08.207 | 131 |
| 3 | Protection | Pickup Due To Negative Phase Sequ... | 04/10/2011 11:24:11.102 | 130 |
| 4 | Trip | DO Trip Due To Negative Phase Seq... | 04/10/2011 11:24:11.242 | 72 |
| 5 | Protection | DropUp Due To Negative Phase Sequ... | 04/10/2011 11:24:24.170 | 131 |
| 6 | Protection | Pickup Due To Negative Phase Sequ... | 04/10/2011 11:24:30.195 | 130 |
| 7 | Trip | DO Trip Due To Negative Phase Seq... | 04/10/2011 11:24:30.335 | 72 |
| 8 | Protection | DropUp Due To Negative Phase Sequ... | 04/10/2011 11:24:36.709 | 131 |
| 9 | Protection | Pickup Due To Negative Phase Sequ... | 04/10/2011 11:24:42.896 | 130 |
| 10 | Trip | DO Trip Due To Negative Phase Seq... | 04/10/2011 11:24:42.806 | 72 |
| 11 | Protection | DropUp Due To Negative Phase Sequ... | 04/10/2011 11:24:52.970 | 131 |

(Figure 4) (Event Data Recording on PC Software)









9) Human Machine Interface

It comprises of bright LCD display

- Four push switches for setting values of normal tripping characteristics and other operations for local access.
- One RESET push switch.
- One push switch for the functions assigned in the HMI to F1 key, 2 push switch to open or close circuit breaker
- Eight LEDs for pickup or tripping on fault and event in any phase.



(Figure 5) (HMI)

| Keys | Manual Key |
|---|---|
|  | is used as intelligent key to see the details of last fault and Relay status. |
|  | is used as a ENTER key. |
|  | is used to manual reset (after pressing for 2 sec). |
|  | is used to scroll in backward direction. |
|  | is used to scroll in forward direction. |
|  | To perform the assigned task either DO trip or Relay reset. |
|  | To open the circuit breaker. |
|  | To close the circuit breaker. |

Output Contacts

| | | |
|------------------------------|---|--|
| No. of digital outputs | : | 4 (DO1, DO2, DO3, DO4) [2 Change over (DO1, DO2), 2 Normal open (DO3, DO4)] |
| Type of outputs | : | Relay |
| Programmable (DO Assignment) | : | Yes |
| Relay reset type | : | Programmable (Auto/Manual) |

Input Contacts

| | | |
|------------------------------|---|---|
| No of digital inputs | : | 6 (DI1, DI2, DI3, DI4, DI5, DI6) for CSENEX-I 202 & 203 model 4 (DI1, DI2, DI3, DI4) for 201 model |
| Type of inputs | : | Depends upon the version |
| Programmable (DI Assignment) | : | Programmable |

10) Communication (Local and Remote)

The unit has:

- * 1 Front USB port for direct connection to a PC
- * 1 Rear RS-485 communication port

a) Rear Communication

The protocol for the rear port is MODBUS-RTU.

b) Front Communication

The entire setting, Fault & Event are available on 'A' type USB (female) interface with CSE LIVELINK with saving & printing option. This unit also has Front-end Live Link simulation support for testing of relay even without any three phase injection source.

11) Setting Ranges

Over Current and Earth Protection

| S. No | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|--|--------------------|-----------------------------|---------------------------|---|--------------------------|
| | | | Min. | Max. | | |
| 1 | Phase characteristics | P-Char | | | DEFT/EINV/VINV /LINV/NINV1.3/ NINV3.0/NINV0.6 | DEFT |
| 2 | Earth Characteristics | E-Char | | | DEFT/EINV/VINV /LINV/NINV1.3/ NINV3.0/NINV0.6 | DEFT |
| 3 | Phase over-current low set pickup setting Phase over-current definite timing Phase over-current inverse timing | I> t> ti> | 0.20xIp 0.05 Sec 0.01 | 4.0xIp 150 Sec 1.50 | 0.01xIp 0.01Sec 0.005 | EXIT 0.10 Sec 0.05 |
| 4 | Phase over-current hi-set pickup setting Phase over-current hi-set definite timing | I>> t>> | 0.5xIp 0.02 Sec | 30xIp 20 Sec | 0.1xIp 0.01Sec | EXIT 0.10 Sec |
| 5 | **Earth over-current low set pickup setting Earth over-current low set definite timing Earth over-current low set inverse timing | Ie> te> tie> | 0.05xIn 0.03 Sec 0.01 | 2.5xIn 150 Sec 1.50 | 0.01xIn 0.01Sec 0.005 | EXIT 0.10 Sec 0.05 |
| 6 | **Earth over-current hi-set pickup setting Earth over-current hi-set definite timing | Ie>> te>> | 0.5xIn 0.02 Sec | 8xIn 20 Sec | 0.05xIn 0.01 Sec | EXIT 0.10 Sec |

Note: All parameters are Password protected

| | | |
|----------------------------|---|-----------|
| Very Inverse | $t = \frac{13.5}{(I/I_s) - 1}$ | $t_i [s]$ |
| Extremely Inverse | $t = \frac{80}{(I/I_s)^2 - 1}$ | $t_i [s]$ |
| Long time Inverse | $t = \frac{120}{(I/I_s) - 1}$ | $t_i [s]$ |
| Normal Inverse 3.0/1.3/0.6 | $t = \frac{0.14/0.061/0.028}{(I/I_s)^{0.02} - 1}$ | $t_i [s]$ |

Where t = Tripping time t_i = Time multiplier
 I = Fault current I_s = Setting value of current

Trip timing Accuracy : DEFT/ NINV 0.6 / NINV 3.0 / 1.3 : $\pm 5\%$ OR $\pm 30\text{mSec}$ (whichever is higher)
 EINV / VINV / LINV : $\pm 7.5\%$ OR $\pm 40\text{mSec}$ (whichever is higher)

Trip Circuit Supervision Protection *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|------------|----------|---------------|-------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Enable TCS | Enable | NO | YES | ----- | NO |
| 2 | TCS | t_TCS | 0.05 Sec | 2 Sec | 0.01 | 0.05 Sec |

Note: t_TCS max setting is 5 Sec for 203 model

Circuit Breaker Failure Protection

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|-------------|-----------|---------------|-------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Enable CBFP | Enable | NO | YES | ----- | NO |
| 2 | CBFP | t_CBFP | 0.05 Sec | 2 Sec | 0.01 | 0.05 Sec |

Note: t_CBFP max setting is 5 Sec for 203 model

Negative Phase Sequence Setting *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|---------------------|---------|---------------|---------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Enable NPS | Enable | NO | YES | ----- | YES |
| 2 | NPS characteristics | Char | DEFT | NPS-INV | ----- | DEFT |
| 3 | Pick up current | I_b | 0.10xlp | 2.5xlp | 0.01xlp | 0.10xlp |
| 4 | Time multiple | K1 | 5.0 | 600 | 1.0 | 5 Sec |
| 5 | Definite time | t_d | 0.10 | 600 | 0.10 | 0.20 Sec |

Note = * Availability as per model selection.

Negative Phase Sequence Equation

$$t = \frac{K1}{(I_2 / I_b)^2 - 1}$$

Where I₂ is injected NPS current.

Trip timing accuracy : $\pm 7.5\%$ OR $\pm 40\text{mSec}$ (whichever is higher)

Broken Conductor Setting *

| S.No. | Parameter | Display | Setting Range Step | | Default Size | Setting |
|-------|-------------------------|--------------------------------|--------------------|--------|--------------|----------|
| | | | Min. | Max. | | |
| 1 | Enable broken conductor | Enable | NO | YES | ----- | NO |
| 2 | NPS-PPS Ratio | I ₂ /I ₁ | 0.10 | 0.50 | 0.01 | 0.10 |
| 3 | Definite trip time | tcon | 0.05 Sec | 20 Sec | 0.01 Sec | 0.05 Sec |

Harmonic Restrain *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|---------------------|----------|---------------|--------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Enable Phase block | PH Block | NO | YES | ----- | NO |
| 2 | Phase Blocking time | tPHASE | 0.0 Sec | 20 Sec | 0.1 | 0.0 Sec |
| 3 | Enable Earth block | E Block | NO | YES | ----- | NO |
| 4 | Earth Blocking time | tEARTH | 0.0 Sec | 20 Sec | 0.1 | 0.0 Sec |

DI Blocking *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|----------------------------|------------------|---------------|-------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Phase over-current low set | I> | Unblock | Block | ----- | Unblock |
| 2 | Phase over-current hi-set | I>> | Unblock | Block | ----- | Unblock |
| 3 | Earth over-current low set | Ie> | Unblock | Block | ----- | Unblock |
| 4 | Earth over-current hi-set | Ie>> | Unblock | Block | ----- | Unblock |
| 5 | Negative Phase sequence | I ₂ > | Unblock | Block | ----- | Unblock |
| 6 | Broken conductor | BC | Unblock | Block | ----- | Unblock |
| 7 | Auto Re-closer | AR | Unblock | Block | ----- | Unblock |

DI Assignment *

| Parameter | Display |
|-----------------|---------|
| Digital Input 1 | DI-1 |
| Digital Input 2 | DI-2 |
| Digital Input 3 | DI-3 |
| Digital Input 4 | DI-4 |
| Digital Input 5 | DI-5 |
| Digital Input 6 | DI-6 |

Note = * Availability as per model selection.

Following functions can be assigned to the 6 DIs

| S.No. | I 201 (Configurable) | I 202 (Configurable) | I 203 (Configurable) |
|-------|----------------------|----------------------|----------------------|
| 1 | CB Close | CB Close | CB Close |
| 2 | CB Open | CB Open | CB Open |
| 3 | Protection Block | CB Ready | CB Ready |
| 4 | Remote Reset | AR Block | AR Block |
| 5 | Remote Trip 1 | Remote Trip 1 | Remote Trip 1 |
| 6 | Remote Trip 2 | Remote Trip 2 | Remote Trip 2 |
| 7 | Remote Trip 3 | Remote Trip 3 | Remote Trip 3 |
| 8 | --- | Protection Block | Protection Block |
| 9 | --- | Remote Reset | Remote Reset |

DO Assignment *

| S.No | Parameter | Display | Setting Range | | Step Size | Default Setting |
|------|------------------------------------|-------------|---------------|------|-----------------|-----------------|
| | | | Min. | Max. | | |
| 1 | Phase over-current low set | I> | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 2 | Phase over-current hi-set | I>> | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 3 | Earth over-current low set | Ie> | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 4 | Earth over-current hi-set | Ie>> | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 5 | Self supervision | SELF SUP | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 6 | Circuit breaker failure protection | CBFP | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 7 | Negative phase sequence | I2> | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 8 | Broken conductor | Broken cond | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 9 | Trip circuit supervision | TCS | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 10 | Circuit breaker open | CB_Open | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 11 | Circuit breaker close | CB_Close | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 12 | Auto Re-closer Relay | AR Close | --- | --- | DO1/DO2/DO3/DO4 | --- |
| 13 | Lockout relay | AR Lockout | --- | --- | DO1/DO2/DO3/DO4 | --- |

Function Reset *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|----------------------------|---------|---------------|--------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Phase over-current low set | I> | Auto | Manual | ----- | Auto |
| 2 | Phase over-current hi set | I>> | Auto | Manual | ----- | Auto |
| 3 | Earth over-current low set | Ie> | Auto | Manual | ----- | Auto |
| 4 | Earth over-current hi set | Ie>> | Auto | Manual | ----- | Auto |
| 5 | Negative phase sequence | I2> | Auto | Manual | ----- | Auto |
| 6 | Broken conductor | BC | Auto | Manual | ----- | Auto |
| 7 | Auto recloser | AR | Auto | Manual | ----- | Auto |

Note = * Availability as per model selection.

Auto Re-closer Mode *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|---|-----------|---------------|---------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Enable Auto-recloser | Enable | Yes | No | | Yes |
| 2 | Dead time 1 | D1 | 0.20 Sec | 300 Sec | 0.01 Sec | 0.20 Sec |
| 3 | Dead time 2 | D2 | 0.20 Sec | 300 Sec | 0.01 Sec | 0.20 Sec |
| 4 | Dead time 3 | D3 | 0.20 Sec | 300 Sec | 0.01 Sec | 0.20 Sec |
| 5 | Dead time 4 | D4 | 0.20 Sec | 300 Sec | 0.01 Sec | 0.20 Sec |
| 6 | Reclaim time | tR | 0.20 Sec | 300 Sec | 0.01 Sec | 0.20 Sec |
| 7 | Phase over-current low set max AR cycle | I>cycle | 2 | 4 | 1 | 2 |
| 8 | Phase over-current hi-set max AR cycle | I>>cycle | 2 | 4 | 1 | 2 |
| 9 | Earth over-current low set max AR cycle | Ie>cycle | 2 | 4 | 1 | 2 |
| 10 | Earth over-current hi-set max AR cycle | Ie>>cycle | 2 | 4 | 1 | 2 |
| 11 | Trip sense time | t_TST | 0.05 Sec | 2 Sec | 0.01 Sec | 0.05 Sec |

Note: t_TST max setting is 5 Sec for 203 model

Key Assignment *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|--------------|---------|---------------|------|--------------------------------|-----------------|
| | | | Min. | Max. | | |
| 1 | Function key | F1 | ---- | ---- | DO1/DO2/DO3 DO4/Relay Reset | DO1 |

Neutral Displacement Setting *

| S.No. | Parameter | Display | Setting Range | | Step Size | Default Setting |
|-------|-----------------------------|---------|---------------|------|-----------|-----------------|
| | | | Min. | Max. | | |
| 1 | Enable neutral displacement | Enable | NO | YES | - | NO |
| 2 | Neutral Voltage | Vn | 2V | 50V | 1V | 7V |

General Setting (These are the settings common for all protections)

| S.No. | Parameter | Display | Setting Range | | Step Max. | Default SizeSetting |
|-------|---------------------|----------------|---------------|----------|-----------|---------------------|
| | | | | Min. | | |
| 1 | Rated phase current | I _p | 1.00 Amp | 5.00 Amp | ----- | 1.00 Amp |
| 2 | Rated earth current | I _n | 1.00 Amp | 5.00 Amp | ----- | 1.00 Amp |
| 3 | Phase CT ratio | PCTRATIO | 1 | 7000 | 1 | 1 |
| 4 | Earth CT ratio | ECTRATIO | 1 | 7000 | 1 | 1 |
| 5 | Nominal frequency | RATDFREQ | 50 Hz | 60 Hz | ----- | 50 Hz |

Rear communication

(*Availability as per Model Selection)

| | |
|------------------------------------|---------------------------------|
| Protocol | MODBUS RTU |
| Baud rate selection (programmable) | 4800/9600/19200/38400/57600bps |
| Parity selection (programmable) | Even / Odd / None |
| Stop bit | 1 Bit |
| Data bit | 8 Bit data |
| Remote Address (programmable) | (1 to 247) |
| Cable required for interface | Two wire twisted shielded cable |

Front communication

| | |
|------------------------------|---|
| Protocol | CSE proprietary protocol: available with front software |
| Baud rate | 19200 bps |
| Cable required for interface | USB cable type (A to A) |

Auxiliary Supply

| | | |
|--------------------------------|----------------------|----------------------------|
| Auxiliary Voltage Range | For L Model | 18V-60V DC |
| | For H Model | 85V-280V AC / 110V-300V DC |
| Supply Range for Digital Input | For L & H Model | Above 24V AC/DC |
| Power Consumption | Quiescent approx. 3W | Operating approx. <7W |

Measurement Accuracy

| S.No | Quantity | Range | Frequency Range | Accuracy |
|------|----------|-------------------------|-----------------|----------|
| 1 | Current | 1 - 30 x I _p | 50 - 60 Hz | ±2% |
| 2 | Voltage | 5 - 40V | 50 - 60 Hz | ±2% |

Pickup Accuracy

| S.No | Quantity | Range | Frequency Range | Accuracy |
|------|----------|-------------------------|-----------------|-----------------------|
| 1 | Current | 1 - 30 x I _p | 50 - 60 Hz | +5% of Pickup setting |
| 2 | Voltage | 5 - 40V | 50 - 60 Hz | +6% of Pickup setting |

12) Technical Data

Measuring Inputs

| | |
|---|---|
| Rated Data | Rated current I _p : 1A or 5A |
| | Rated frequency F _n : 50 Hz/60Hz |
| Drop out to Pickup Ratio | >96% |
| Power consumption in current circuit | At I _p =1A 0.2 VA |
| | At I _p =5A 0.4 VA |
| Thermal withstand capability in current circuit | Dynamic current withstand |
| | (half wave): 250 x I _p |
| | for 1 Sec : 100 x I _p |
| | for 10 Sec : 30 x I _p |
| | continuously : 4 x I _p |

Trip Contact Rating

| | |
|------------------------------|-------------------------------------|
| Contact Rating | |
| Contact relay | Dry contact Ag Ni |
| Make current | Max. 30A & carry for 3S |
| Carry capacity | 8A continuous : Relay 1 |
| | 4A continuous : Relay 2, 3, 4 |
| Rated voltage | 250V AC/ 30V DC |
| DC Current Carrying Capacity | 8A@30VDC / 0.3A@110VDC/ 0.2A@220VDC |
| Breaking Characteristics | |
| Breaking capacity AC | 1500VA resistive |
| | 1500VA inductive (PF=0.5) |
| Breaking capacity DC | 220V AC, 5A ($\cos\phi \leq 0.6$) |
| | 135V DC, 0.3A (L/R=30ms) |
| | 250V DC, 50W resistive or |
| | 25W inductive (L/R=40ms) |
| Operation time | <10ms |
| Durability | |
| Loaded contact | 10,000 operation minimum |
| Unloaded contact | 30,000 operation minimum |

Over-voltage category : II, Insulation voltage : 300V, Pollution Degree : 2, IP 54 from Front

13) Type Test

| | |
|--|--|
| DESIGN STANDARD | |
| Specified ambient service temp. range | VDE 04355 part 303, IEC 255-4, BS 142 |
| For storage | 40 degC to + 85 degC |
| For operation | -20 degC to 70 degC |
| Environmental protection class F as per DIN 40040 and per DIN IEC 68, part 2.3 | relative humidity 95% at 40 deg C for 56 days. |
| Isolation test voltage, inputs and outputs between themselves and to the relay frame as per VDE 0435, part 303 | 2.5 KV (eff.) / 50 Hz, 1 min. |
| Impulse test voltage, inputs and outputs between themselves and to the relay frame as per VDE IEC 0435, part 303 | 5 KV, 1.2/50ms, 0.5J |
| High frequency interference test voltage, inputs and outputs between themselves and to the relay frame as per DIN IEC 255, part 22-1 | 2.5 KV/1MHz |
| Electrical fast transient (burst) test as per DIN VDE 0843 part 4 | 4KV / 2.5 kHz, 15ms |
| Radio interference suppression test as per DIN VDE 57 871 | Limit value class B |
| Electrostatic discharge (ESD) test as per DIN VDE 0843 part 2 | 8 KV |
| Radiated electromagnetic field test as per VDE 0843 part2 | 10 V/m |

14) Technical Test

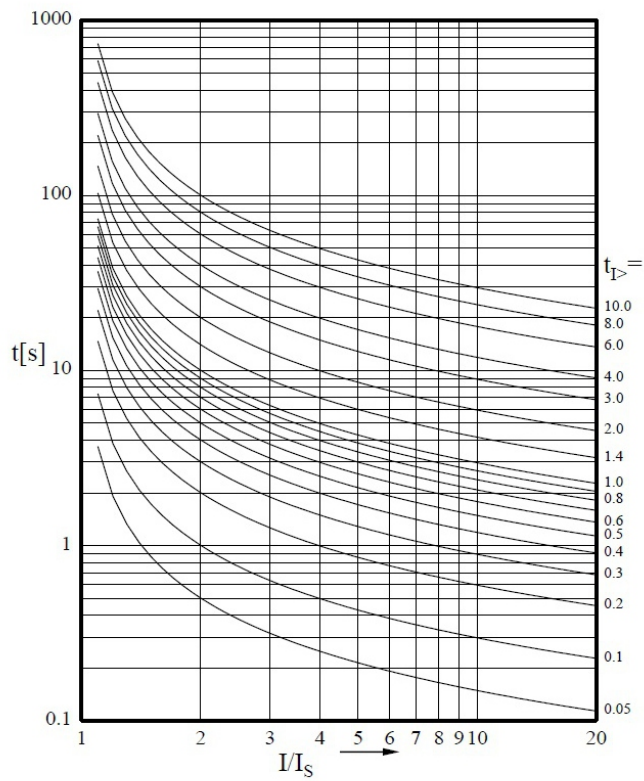
| | |
|------------------------|--------------------------------------|
| Shock | As per DIN IEC 41 B (CO) 38: class 1 |
| Vibration | As per DIN IEC 41 B (CO) 35: class 1 |
| Protection-Front Panel | IP 54 |
| Protection-Rear Panel | IP 00 |
| Weight | Approx. 1.0 Kg |

15) Model Selection Table

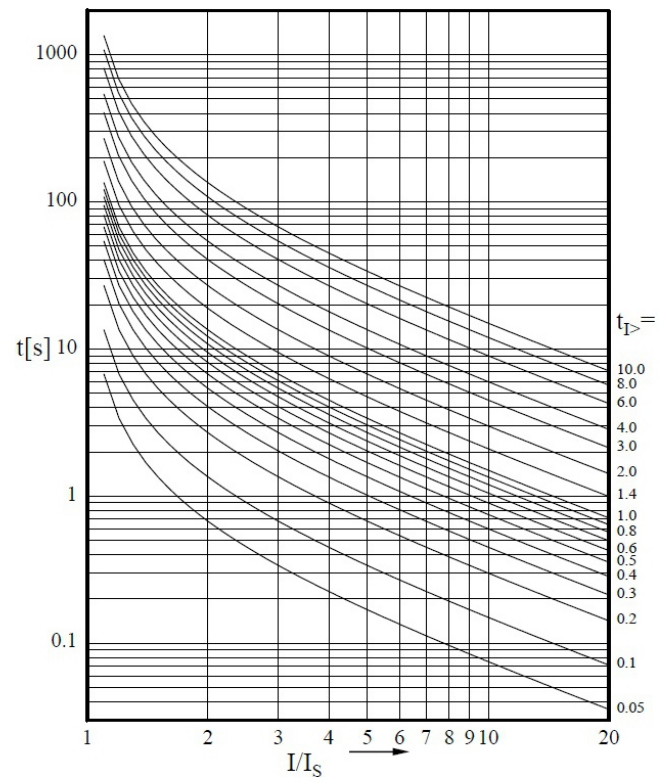
| Function | ANSI | NEX-I 201 | NEX-I 202 | NEX-I 203 |
|----------------------|---------|---------------------------------|------------------------------|------------------------------|
| CT inputs | - | 4 | 4 | 4 |
| PT inputs | - | x | x | 1 |
| Over current | 50/51 | ✓ | ✓ | ✓ |
| Earth Fault | 50N/51N | ✓ | ✓ | ✓ |
| Neutral displacement | 59N | x | x | ✓ |
| CBFP | 50BF | ✓ | ✓ | ✓ |
| Unbalance | 46 | ✓ | ✓ | ✓ |
| Trip circuit | 74TC | ✓ | ✓ | ✓ |
| Harmonic blocking | 50H | ✓ | ✓ | ✓ |
| Broken conductor | 46BC | x | ✓ | ✓ |
| Auto Re-closer | 79 | x | ✓ | ✓ |
| Digital input | - | 4 | 6 | 6 |
| Digital output | - | 4 | 4 | 4 |
| Fault record | - | 10 | 10 | 10 |
| Event record | - | 50 | 50 | 50 |
| Selection of 1/5A | - | Site selectable | Site selectable | Site selectable |
| Enclosure type | - | Draw out with CT CT shorting | Draw out with CT shorting | Draw out with CT shorting |
| Enclosure (WxHxD) mm | - | (125x154x156) | (125x154x156) | (125x154x156) |
| Front communication | - | ✓ | ✓ | ✓ |
| Rear comm. (RS-485) | - | ✓ | ✓ | ✓ |

Inverse Graph Representation

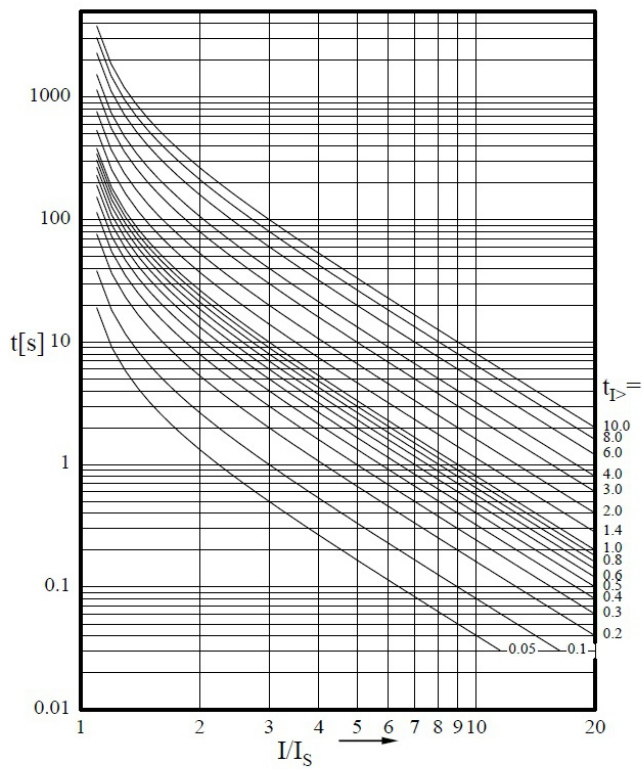
Inverse Time Characteristics



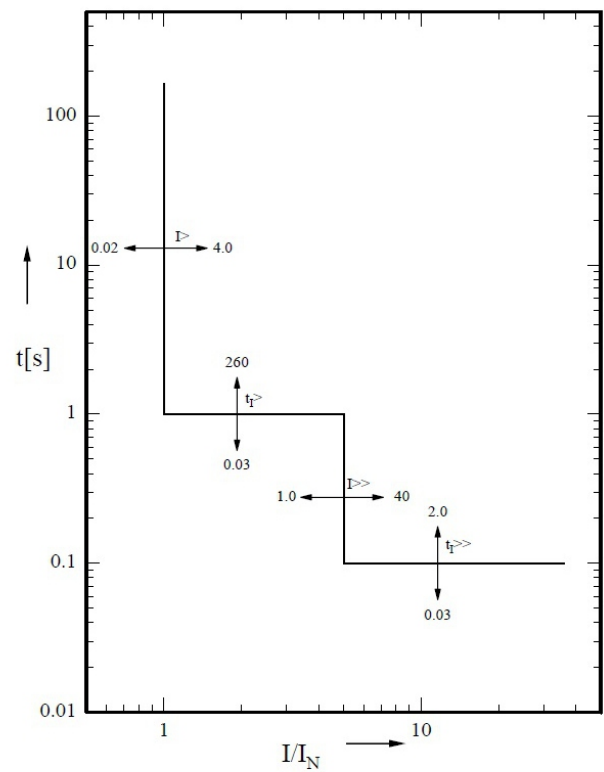
Normal Inverse



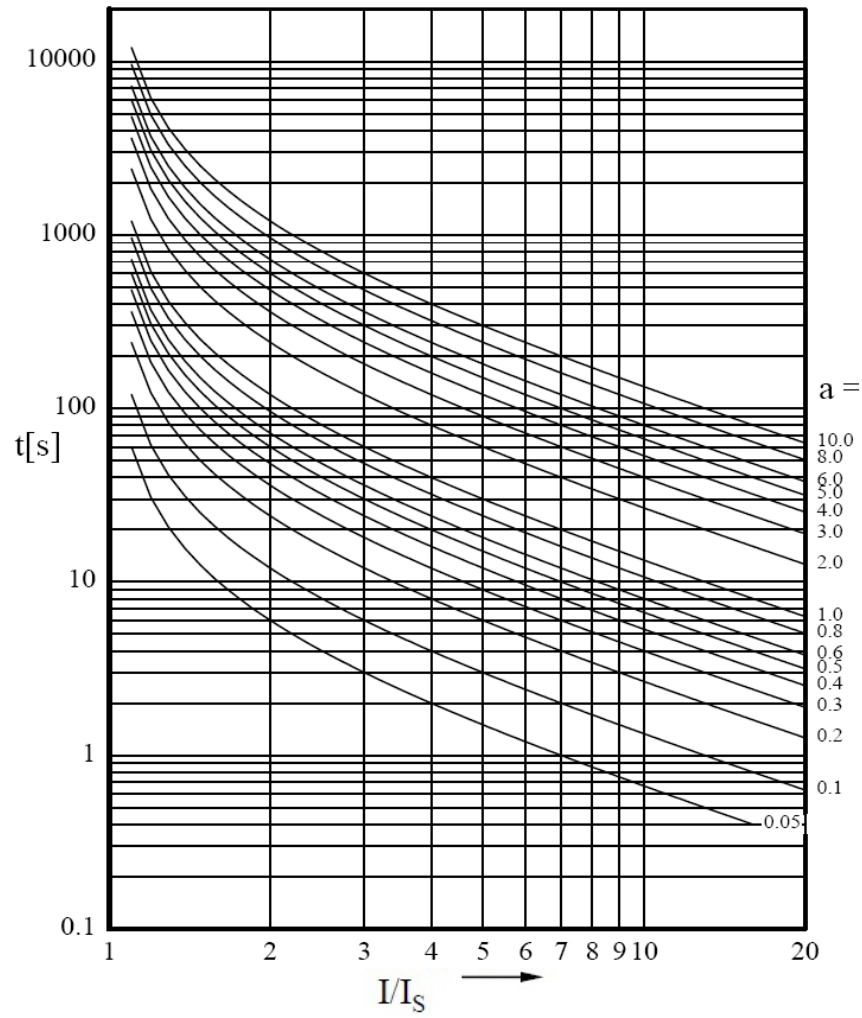
Very Inverse



Extremely Inverse



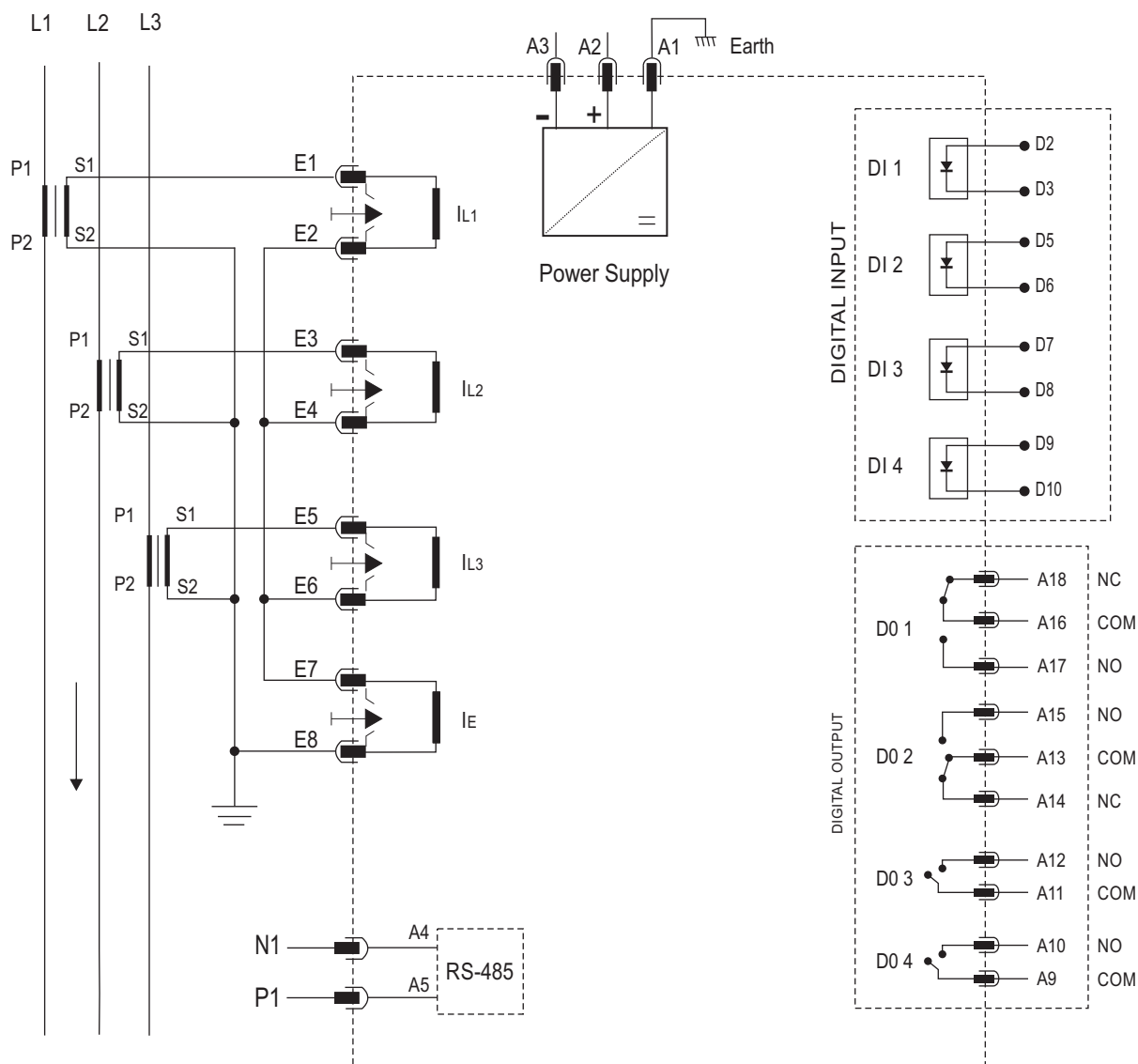
Definite time overcurrent relay



Long time inverse

16) Connection Diagram

CSENEX-I 201



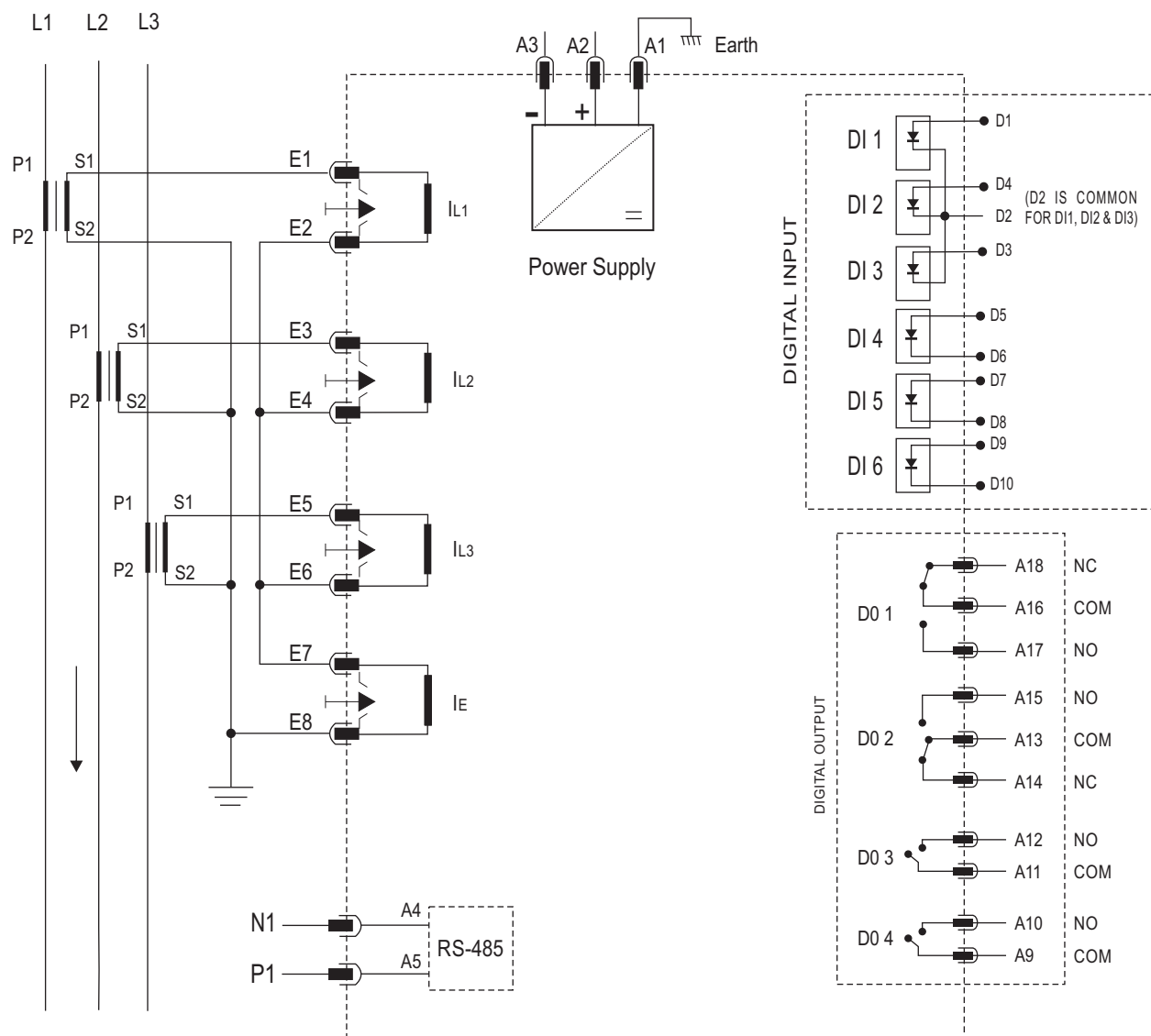
(Figure 7)

Terminal Description

| Terminal Name | Terminal Description |
|---------------|---|
| A1 | : Power Supply Earth |
| A2-A3 | : Power Supply |
| A4-A5 | : RS-485 Modbus N1(A4), P1(A5) |
| A9-A10 | : Potential free Digital Output 4 |
| A11-A12 | : Potential free Digital Output 3 |
| A13-A14-A15 | : Potential free Digital Output 2 |
| A16 -A17- A18 | : Potential free Digital Output 1 |
| D3-D2 | : Potential Digital Input 1 |
| D5-D6 | : Potential Digital Input 2 |
| D7-D8 | : Potential Digital Input 3 |
| D9-D10 | : Potential Digital Input 4 |
| E1-E6 | : CT Terminal for Phase current input L1(E1-E2), L2(E3-E4), L3(E5-E6) |
| E7-E8 | : CT Terminal for Earth current input |

Connection Diagram

CSENEX-I 202



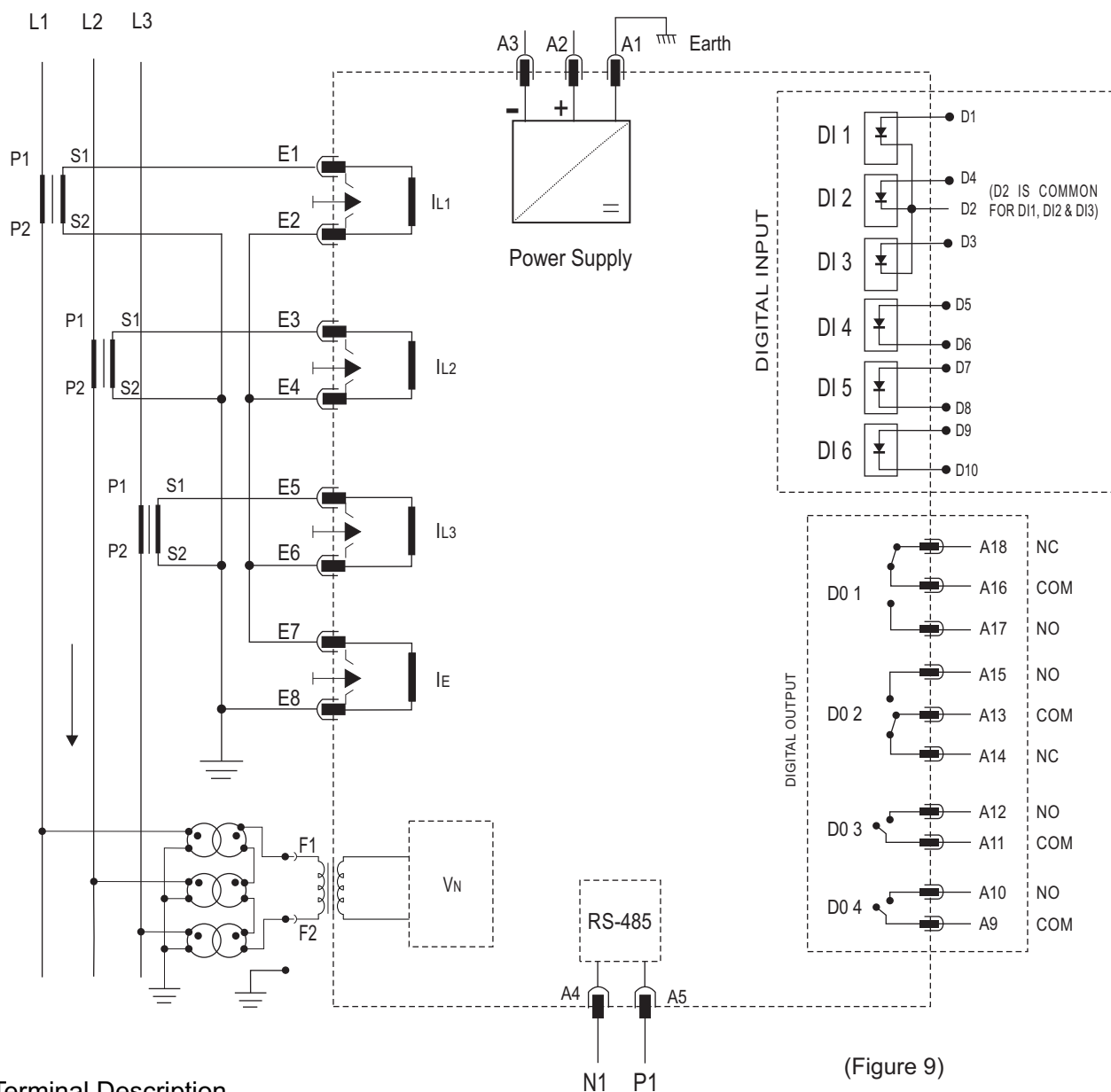
(Figure 8)

Terminal Description

| Terminal Name | Terminal Description |
|---------------|--|
| A1 | : Auxiliary Supply Earth |
| A2-A3 | : Auxiliary Supply |
| A4-A5 | : RS-485 Modbus N1(A4), P1(A5) |
| A9-A10 | : Potential free Digital Output 4 |
| A11-A12 | : Potential free Digital Output 3 |
| A13-A14-A15 | : Potential free Digital Output 2 |
| A16 -A17- A18 | : Potential free Digital Output 1 |
| D1-D2 | : Potential Digital Input 1 |
| D4-D2 | : Potential Digital Input 2 |
| D3-D2 | : Potential Digital Input 3 |
| D5-D6 | : Potential Digital Input 4 |
| D7-D8 | : Potential Digital Input 5 |
| D9-D10 | : Potential Digital Input 6 |
| E1-E6 | : CT Terminal for Phase current input L1(E1-E2), L2(E3-E4),L3(E5-E6) |
| E7-E8 | : CT Terminal for Earth current input |

Connection Diagram

CSENEX-I 203

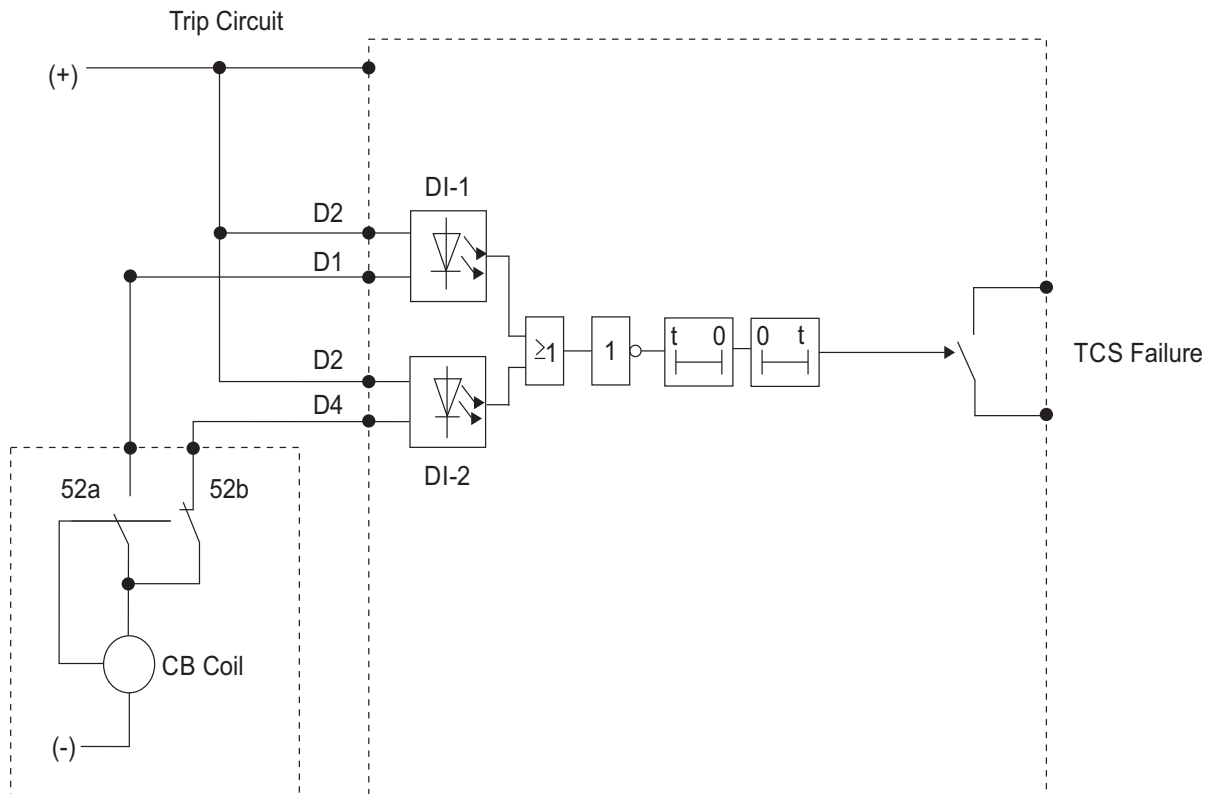


(Figure 9)

Terminal Description

| Terminal Name | Terminal Description |
|---------------|--|
| A1 | Auxiliary Supply Earth |
| A2-A3 | Auxiliary Supply |
| A4-A5 | RS-485 Modbus N1(A4), P1(A5) |
| A9-A10 | Potential free Digital Output 4 |
| A11-A12 | Potential free Digital Output 3 |
| A13-A14-A15 | Potential free Digital Output 2 |
| A16 -A17- A18 | Potential free Digital Output 1 |
| D1-D2 | Potential Digital Input 1 |
| D4-D2 | Potential Digital Input 2 |
| D3-D2 | Potential Digital Input 3 |
| D5-D6 | Potential Digital Input 4 |
| D7-D8 | Potential Digital Input 5 |
| D9-D10 | Potential Digital Input 6 |
| E1-E6 | CT Terminal for Phase current input L1(E1-E2), L2(E3-E4),L3(E5-E6) |
| E7-E8 | CT Terminal for Earth current input |
| F1-F2 | PT Terminals |

Trip Circuit Supervision

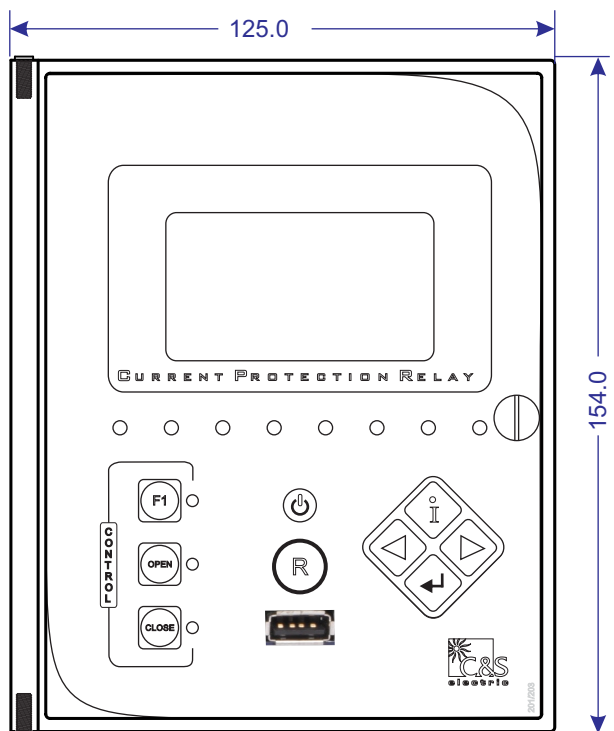


(Figure 10)

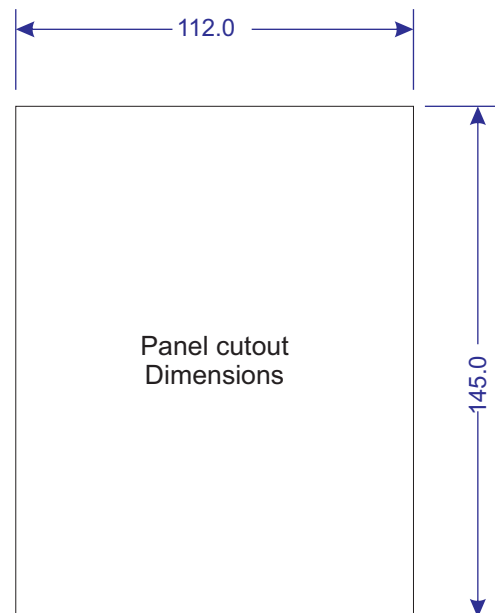
(Note: CB coil resistance should be such that at least 4mA current must flow in each Digital Input)

18) Dimensional Details

Front View

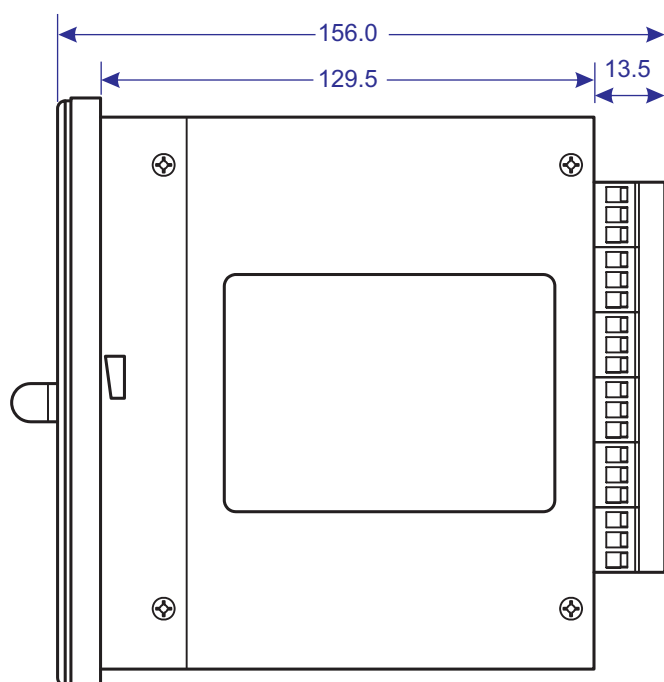


(Figure 12)



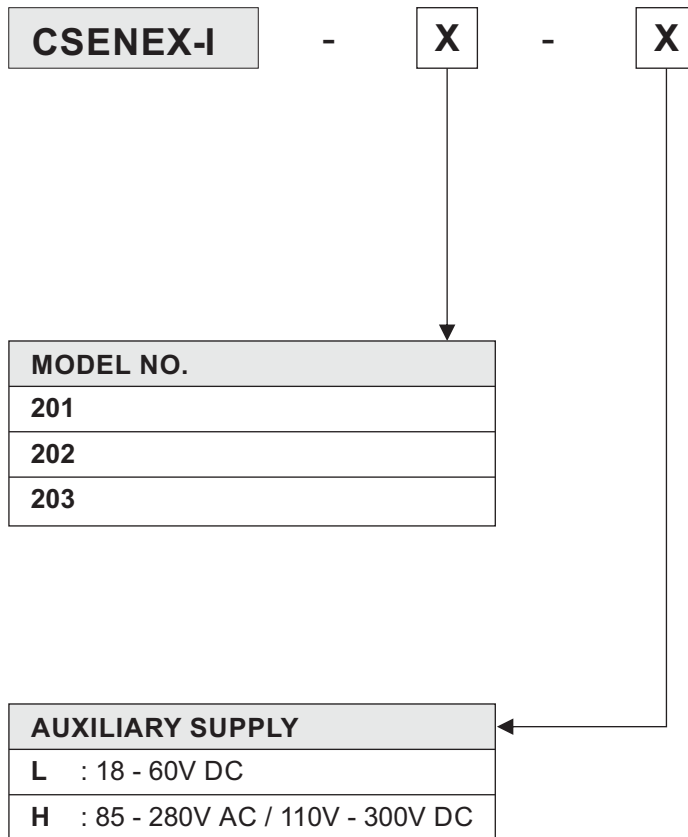
(Figure 13)

Side View



(Figure 14)

19) Ordering Information



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